

Hyperspectral remote sensing of coral reefs by semi-analytical model inversion

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Comparison of inversion schemes

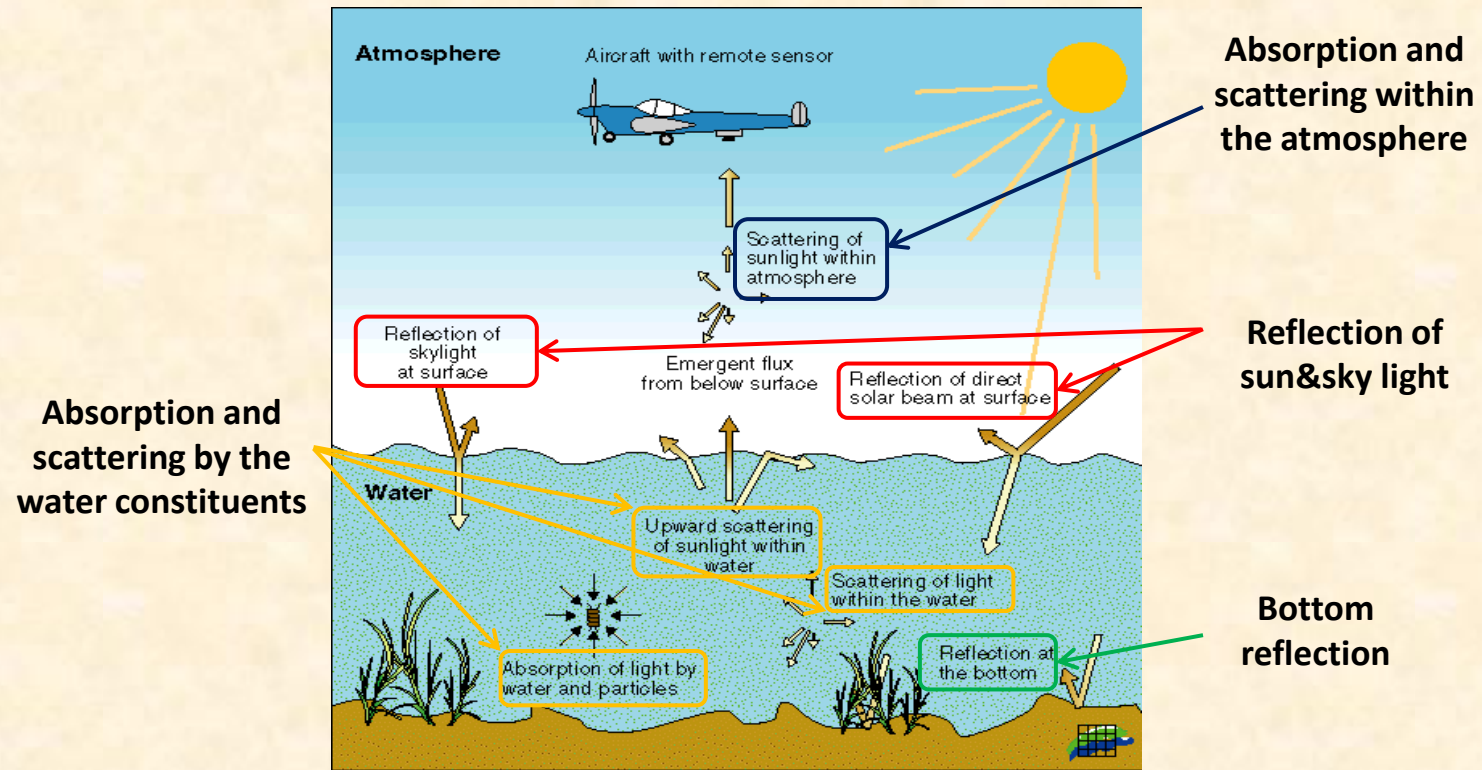
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Introduction – From sun to sensor...



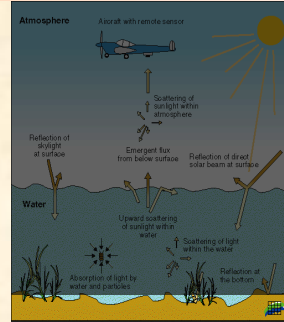
Bertels et al., 2008

GOAL : Retrieve **bottom depth** and **seabed types** from the sub-surface reflectance (i.e. after atmospheric and sea-surface corrections)

METHOD :

1. **Build a direct model** expressing the sub-surface reflectance as a function of the environmental conditions
2. **Inverse the direct model** so as to retrieve the desired bio-physical quantities

Direct model – Bottom reflectance



- Linear mixing of four known endmembers

$$\rho_B = [\rho_{coral} \quad \rho_{algae} \quad \rho_{seagrass} \quad \rho_{sand}]. \mathbf{x} = \mathbf{E} \cdot \mathbf{x}$$

ρ_B : Bottom reflectance (n x 1)

\mathbf{E} : Endmember matrix (n x 4)

\mathbf{x} : Abundance vector (4 x 1)

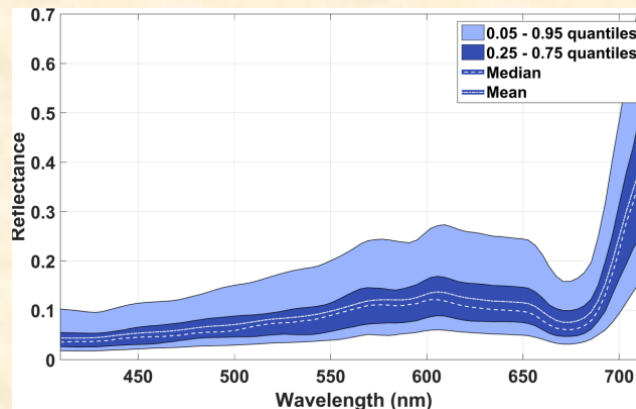
n : Number of spectral bands

- Endmember matrix construction

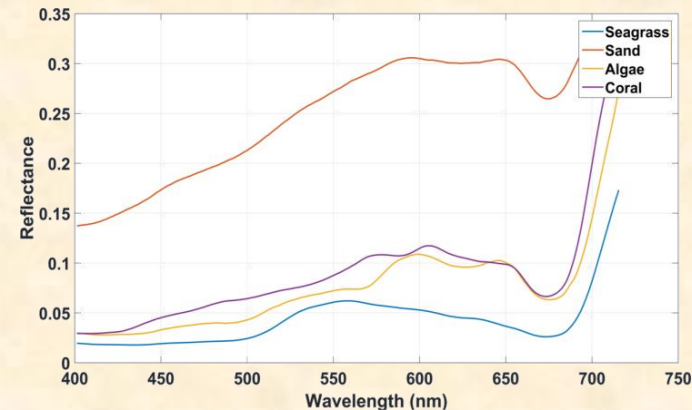
1. *In-situ* measurements enabled constituting a spectral library
2. Statistics were computed for each class of the spectral library
3. Mean spectrum of each class was retained as the corresponding endmember



Reflectance measurement of a *Porites sp.*



Submassive corals spectral statistics



Reflectances of the four retained endmembers

➔ ρ_B expressed as a function of 4 unknowns, which are the abundances of coral, algae, seagrass and sand.

Direct model – Water column

- **Four kinds of « optically active » water constituents**

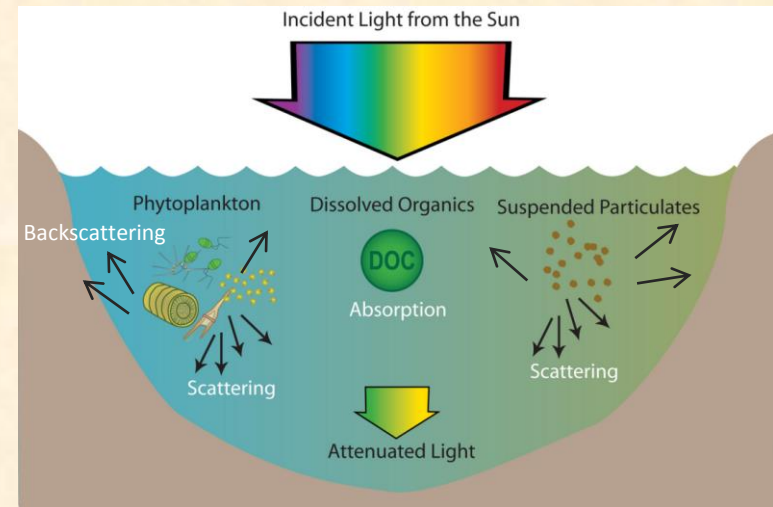
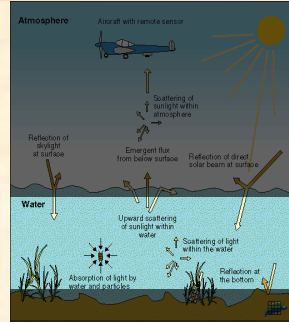
- Pure water
- Colored dissolved organic matter (CDOM)
- Phytoplankton (phy)
- Non algal particles (NAP)

Concentration vector : $\mathbf{C} = [C_{phy} \quad C_{CDOM} \quad C_{NAP}]$

- **Two kinds of quantities modeled according to *Brando et al., 2009***

- Water reflectance : $r_{rs}^{dw} = f_1(\lambda, \mathbf{C})$
- Water diffuse attenuation : $\begin{cases} k_d = f_2(\lambda, \mathbf{C}) \\ k_u^c = f_3(\lambda, \mathbf{C}) \\ k_u^b = f_4(\lambda, \mathbf{C}) \end{cases}$

Water column reflectance and diffuse attenuation coefficients expressed as functions of 3 unknowns, namely the concentrations of phytoplankton, CDOM and NAP



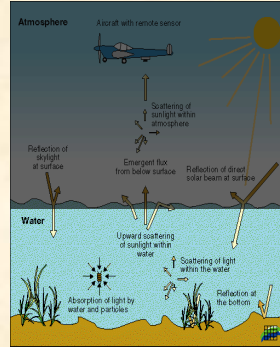
Direct model – Surface reflectance

- **Surface reflectance model** (Lee et al., 1998)

$$r_{mod}^{-}(\lambda) = r_{rs}^{dw}(\lambda) \left[1 - e^{-(k_d(\lambda) + k_u^C(\lambda))H} \right] + \frac{1}{\pi} \rho_B(\lambda) e^{-(k_d(\lambda) + k_u^B(\lambda))H}$$

r_{mod}^{-} : Modeled subsurface reflectance

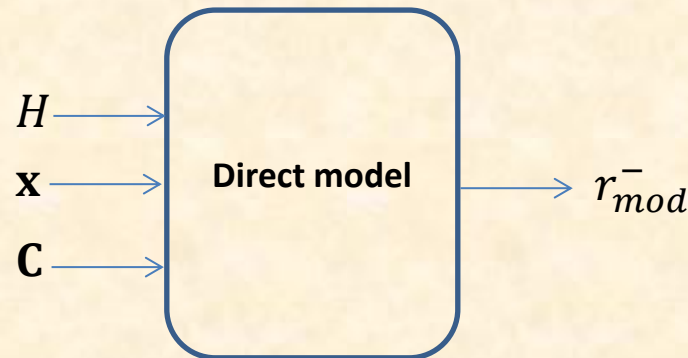
H : Bottom depth



- **A priori inclusion**

$$r_{mod}^{-}(\lambda, H, \mathbf{x}, \mathbf{C}) = f_1(\lambda, \mathbf{C}) \left[1 - e^{-(f_2(\lambda, \mathbf{C}) + f_3(\lambda, \mathbf{C}))H} \right] + \frac{1}{\pi} \sum_i E_i(\lambda) \cdot x_i \cdot e^{-(f_2(\lambda, \mathbf{C}) + f_4(\lambda, \mathbf{C}))H}$$

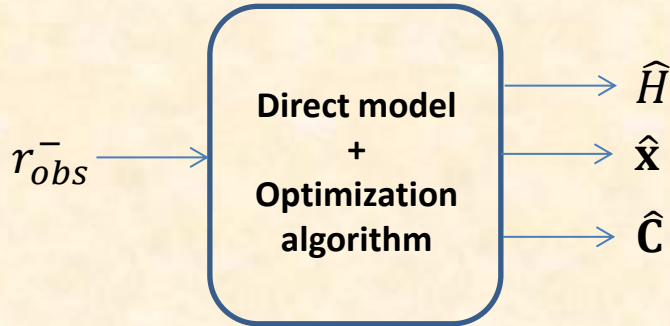
- **Direct model synoptic**



➡ Subsurface reflectance expressed as a function of 8 scalars : bottom depth (H), four seabed abundances (\mathbf{x}) and three water column constituent concentrations (\mathbf{C})

Model inversion – global formulation + confounding factors

- Inverse model synoptic



- Mathematical formulation

$$[\hat{H} \quad \hat{\mathbf{x}} \quad \hat{\mathbf{C}}] = \arg \min_{\mathbf{C}, \mathbf{x}, H} c(r_{obs}^-; r_{mod}^-(H, \mathbf{x}, \mathbf{C}))$$

s. t some constraints



Need to define a proper cost function c as well as relevant constraints on \mathbf{C} , \mathbf{x} and H .

- Issues that should be taken into account when choosing the cost function & optimization constraints :
 - Residual sun&sky sea surface reflections (low frequency additive noise)
 - Residual atmospheric effects (low frequency additive&multiplicative noise)
 - Amplitude variability of the seabed endmembers (flat multiplicative noise)

- **Cost function**

- **Least squares** ($c_{LS}(a; b) = \|a - b\|_2$)

Most natural cost function for curve fitting but very sensitive to non zero-mean noise

- **Spectral angle mapper** ($c_{SAM}(a; b) = \frac{\langle a, b \rangle}{\|a\|_2 \cdot \|b\|_2}$)

Robust to multiplicative low-frequency noise, but loses part of the information

- **Least squares on first spectral derivative** ($c_{LSD}(a; b) = \|(a - b) * sg_{3,7}^1\|_2$; sg : savitsky-golay filter)

Robust to additive low-frequency noise, but loses part of the information

- **Constraints on seabed abundances (x vector)**

- **Abundance sum-to-one constraint (ASC: $\|x\|_1 = 1$)**

Strictly respects the physics of the problem under ideal conditions (perfect endmembers and linear mixture)

- **Relaxed abundance sum-to-one constraint (RASC: $0.5 < \|x\|_1 < 2$)**

Can take into account part of the amplitude variability of the endmembers

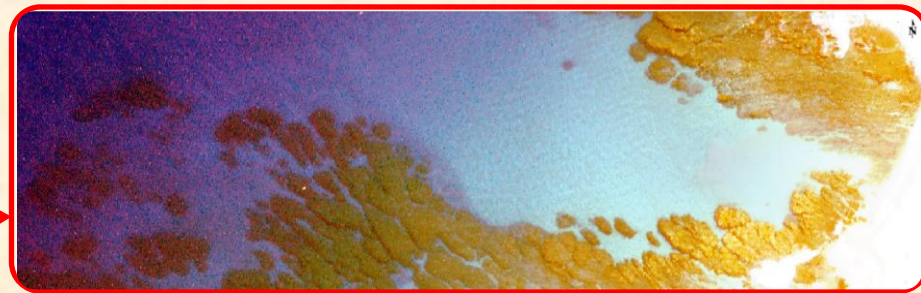
➡ **3 cost functions x 2 seabed constraints = 6 inversion schemes to be assessed**

Study sites



Indian Ocean Litto3d cruise : Flight lines of hyperspectral acquisitions over La Réunion

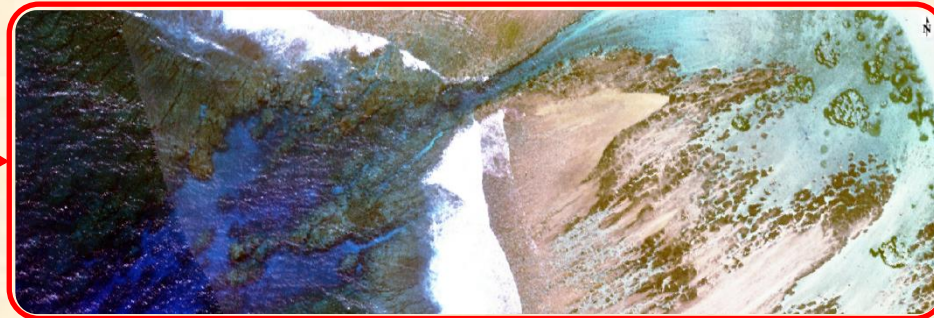
Boucan



- Homogeneous seabed
- Low bathymetric gradient

Flight lines over Saint-Gilles coastline

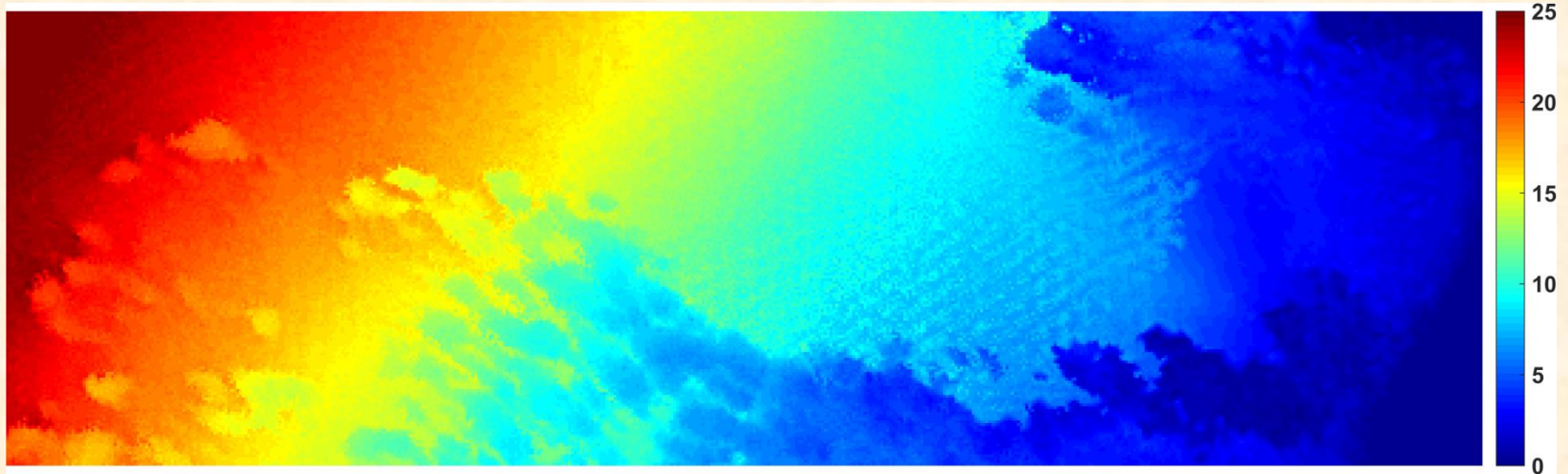
Ermitage



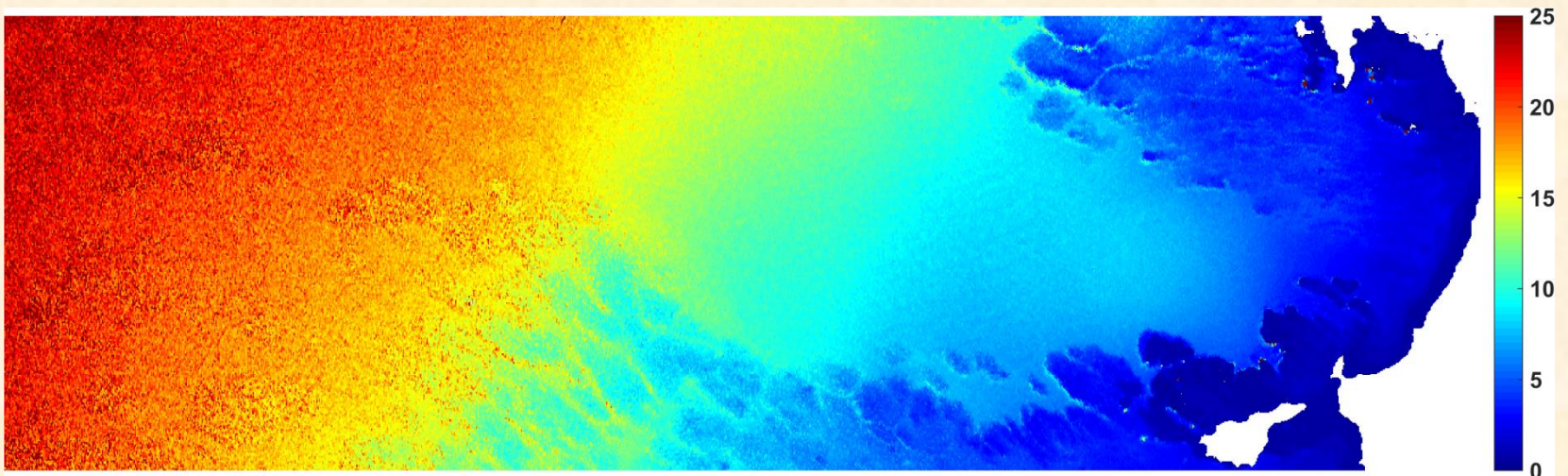
- Heterogeneous seabed
- Inner vs Outer reef

Results – Bathymetry on Boucan

- Result example
 - LIDAR bathymetry

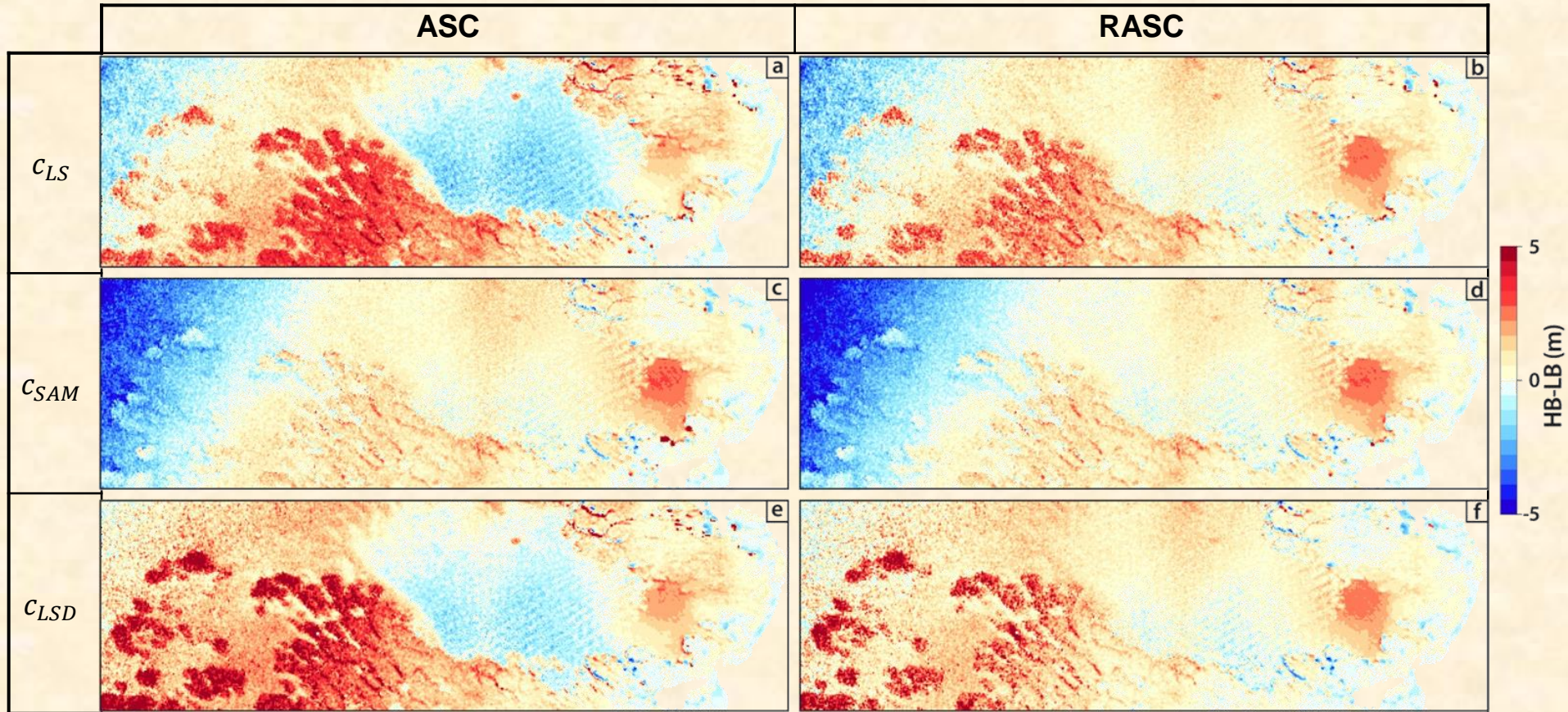


- Hyperspectral bathymetry (RASC-LS based inversion)



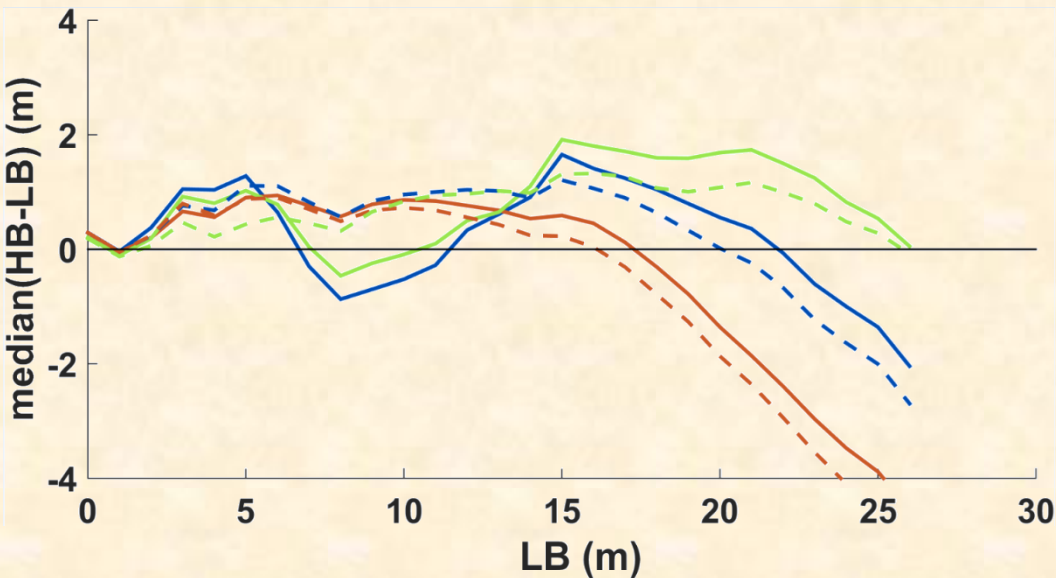
Results – Bathymetry on Boucan

- Differential maps between hyperspectral and Lidar bathymetry (HB and LB)



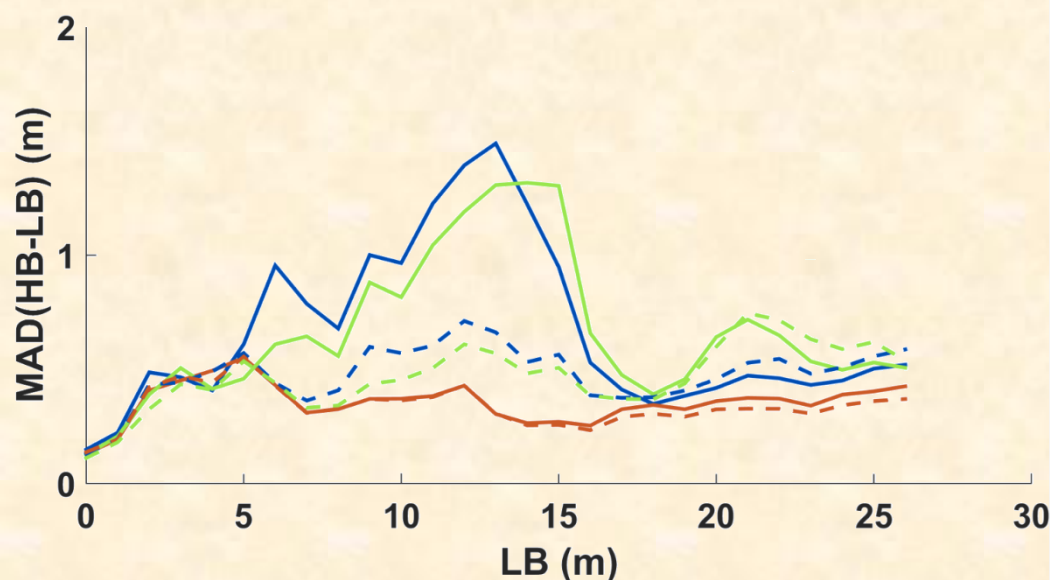
Results – Bathymetry on Boucan

- **Median estimation error**



- Interest of using LSD at high depths
- More stable estimation with RASC for LS&LSD cost functions

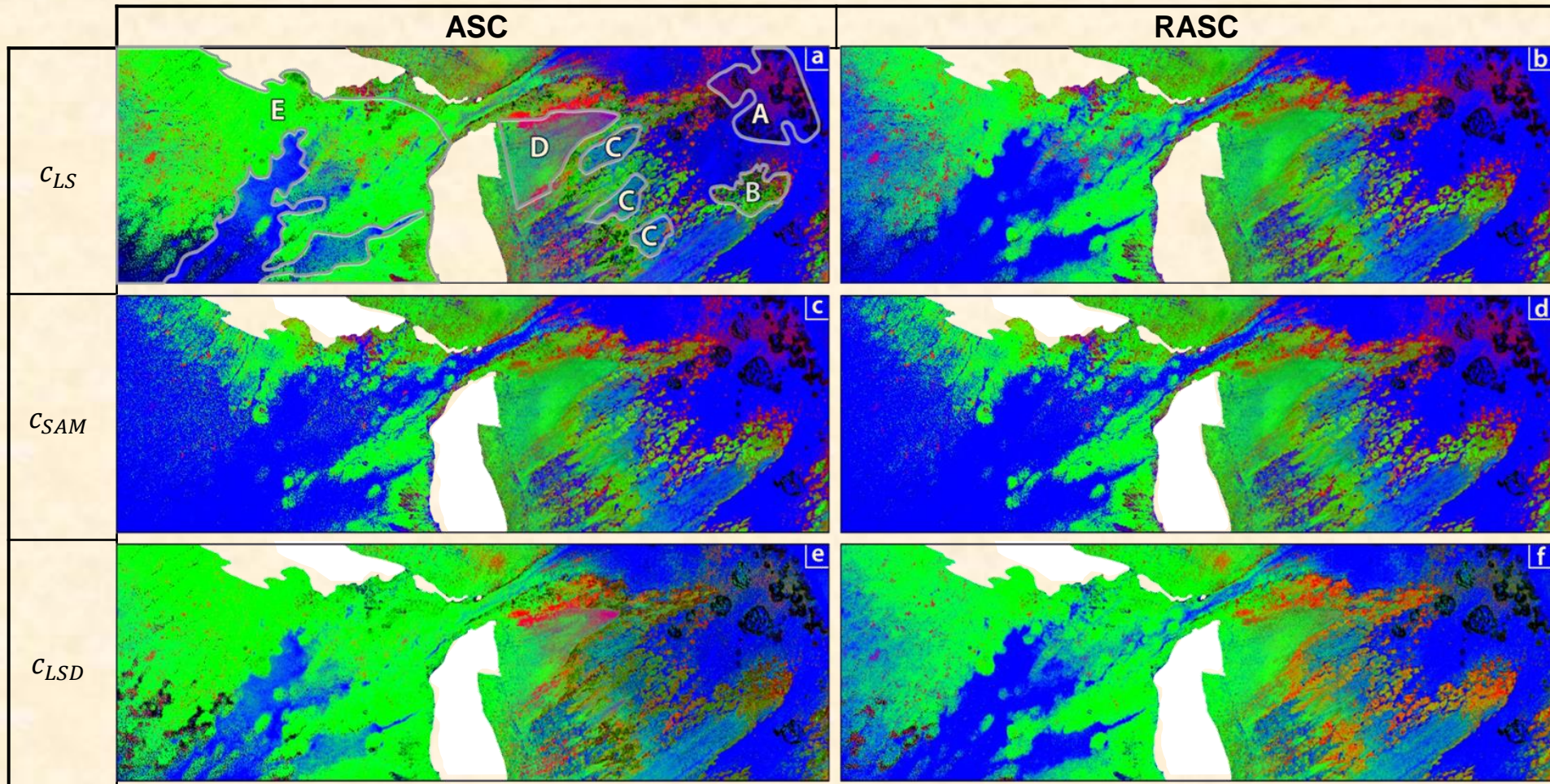
- **Median absolute deviation**



- SAM shows the lowest dispersion
- Very positive impact of RASC for LS&LSD cost functions

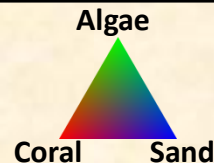
Results – Seabed type retrieval on Ermitage

- Composite abundance maps (R=coral; G=algae; B=sand; darkness=seagrass)



Outer reef (left part of the study site) :

- ASC enables differentiating seabed types deeper than RASC
- Inefficiency of SAM for mapping seabed in deep areas
- Instability issues with LSD in deep areas

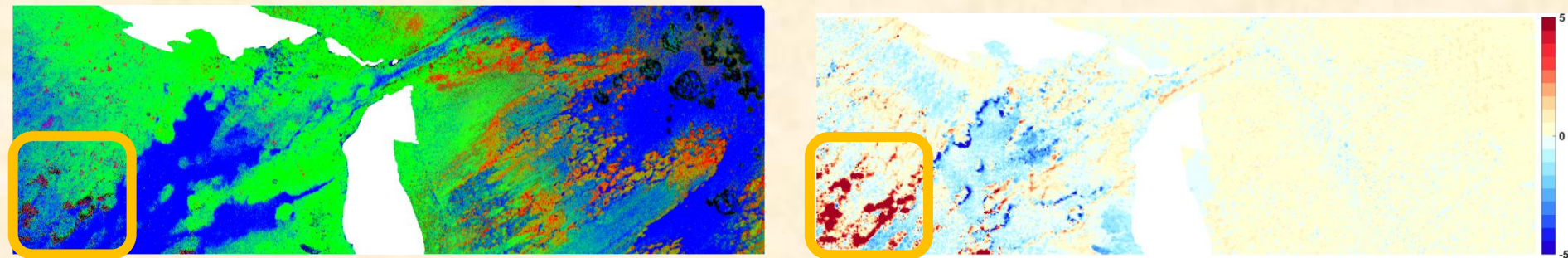


Inner reef (right part of the study site):

- Algae surrounding seagrass (zone A) correctly identified by LSD-based inversion schemes
- Enhancement of coral detection with RASC-LSD (e.g. zone B)

On the potential benefit of regularization...

- Instability issue with RASC-LSD on deep area



ill-conditioned problem ?

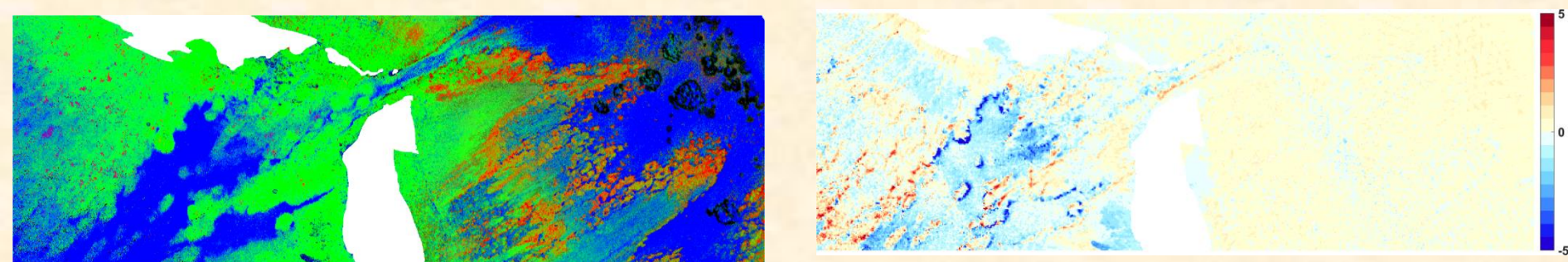
- Addition of a regularization term to the cost function (*Jay&Guillaume, 2016*)

$$c_{LSD}(r_{obs}^-; r_{mod}^-(H, \mathbf{x}, \mathbf{C})) = \|(r_{obs}^- - r_{mod}^-(H, \mathbf{x}, \mathbf{C})) * sg_{3,7}^1\|_2$$



$$c_{LSDR}(r_{obs}^-; r_{mod}^-(H, \mathbf{x}, \mathbf{C})) = \|(r_{obs}^- - r_{mod}^-(H, \mathbf{x}, \mathbf{C})) * sg_{3,7}^1\|_2 + \lambda \cdot H$$

- Results obtained with RASC-LSDR ($\lambda = 10^{-5}$)



Conclusion

- **Bathymetry**
 - Great potential of hyperspectral imaging for predicting bathymetry down to 15-20 m depth
 - SAM was the least sensitive cost function to changes in seabed type
 - LSD cost function gave the best results at high depths
 - Use of RASC decreased error dispersion compared to ASC
- **Seabed types**
 - Very accurate results at low depths (<2 m) with RASC-LSD algorithm
 - SAM was not able to differentiate seabed types from ~5 m depth
 - ASC-LS provided the most consistent results at high depths
 - LSD-based inversion schemes suffered from instability issues at high depth

➡ There is no optimal inversion scheme for estimating all the parameters at all the depths.

➡ Future work should focus on the formalization of prior knowledge into relevant regularization terms.

Merci pour votre attention