Integrating water column effects and bottom neighbor influence for a specific NMF seabed unmixing method



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Objective

Develop an advanced method for unmixing the seabed in coastal areas

Mixing model

The mixing model is ⁽¹⁾

 $\widetilde{\mathbf{R}} = \mathbf{K}_1 \odot \ (\mathbf{S} \ \mathbf{A}) + \mathbf{K}_2 \odot \ (\mathbf{S} \ \mathbf{A} \ \mathbf{P})$

 $\widetilde{\mathbf{R}}$: $\mathbf{R} - \left(\frac{\mathbf{L}_{u}^{dp}}{\mathbf{E}(0-)}\right)$; observed reflectance – water reflectance (L wavelengths X N pixels)



 \mathbf{K}_1 : water direct attenuation ; \mathbf{K}_2 : water diffuse attenuation (L X N) ; \bigcirc : pointwize product (Hadamard) \mathbf{S} : bottom endmembers matrix (L X J endmembers) \mathbf{A} : bottom abundances matrix (J X N) \mathbf{P} : neighbor matrix (with environment parameter included) (N X N)Bottom: linear mixing model $\mathbf{X} = \mathbf{S} \mathbf{A}$ The water attenuates and diffuses the photons reflected by the bottom.The photons diffused after interaction with pixels adjacent to the target one

participate in the diffused light L_{dif} ⁽²⁾. The matrix **P** selects the neighbor pixels to account for the diffusion.

Unmixing

Unmixing is performed by minimizing the cost function *J*:

 $J = \arg \min_{S,A} \|\widetilde{\mathbf{R}} - \mathbf{K}_1 \odot (\mathbf{S} \mathbf{A}) - \mathbf{K}_2 \odot (\mathbf{S} \mathbf{A} \mathbf{P})\|_F^2 + \operatorname{reg}(\mathbf{S}, \mathbf{A})$

The regularization term reg(**S**,**A**) can be the abundance sum to one constraint or other.

Optimization: gradient descent on S and A, K_1 and K_2 are supposed known.

Results on simulated data

Comparison between NMF with no water, NMF for underwater data without modelling adjacency effects (P=I, algorithm WUM) and NMF for underwater data and modelling adjacency (algorithm WADJUM).





The scene is from the coastal zone of Porquerolles Island, France.

- The airborne images were acquired by Hytech Imaging
- Water quality measurements were conducted to calculate K_1 , K_2 : Chl= 0.03 mg m⁻³, SM = 0.5 mg L⁻¹, Cdom = 0.05 m⁻¹
- Bathymetry from Litto-3D was used



Abundance maps obtained with WADJUM. The spectral library is used for initialization of endmembers, abundances are initialized with estimated coefficients.

Spectral mean error (SME) and abundance mean error (AME) for clear water: $Chl = 0.03 \text{ mg m}^{-3}$, $SM = 0.01 \text{ mg }L^{-1}$, $Cdom = 0.01 \text{ m}^{-1}$, and moderately turbid (standard) water : $Chl = 1 \text{ mg m}^{-3}$, $SM = 1 \text{ mg }L^{-1}$, $Cdom = 0.1 \text{ m}^{-1}$

Conclusion

- We have developed a new NMF, taking into consideration the adjacency effect for underwater unmixing.
- Simulations show that the model is necessary to unmix sea bottom with moderately turbid water (H>3m), and also improves the results for clear water (H>5m)
- Results on real data
- Perspectives : study with unknown water quality

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